

Towards a Foundation Model for Fusion: Multimodal Representation Learning of Plasma State and Control





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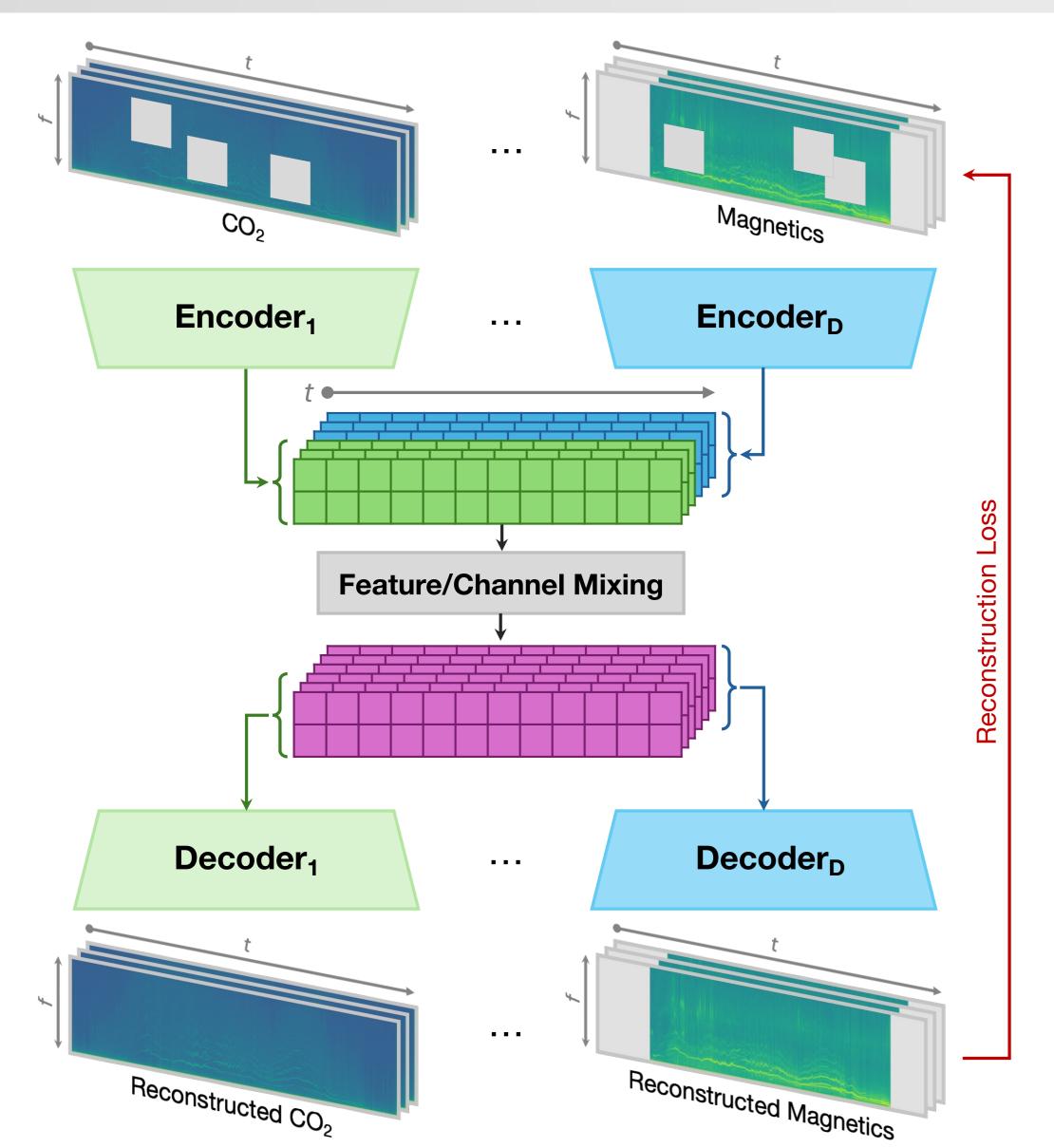
Motivation

- Foundation models: Large neural nets pre-trained on diverse data to learn general-purpose representations adaptable to multiple downstream tasks.
- **Diagnostic fusion:** Building on the success of *Diag2Diag* [1], we seek to integrate multiple diagnostics to build a foundation model for fusion.
- Self-supervised learning is able to leverage large-scale multi-modal data to learn a universal representation of plasma dynamics.

Dataset

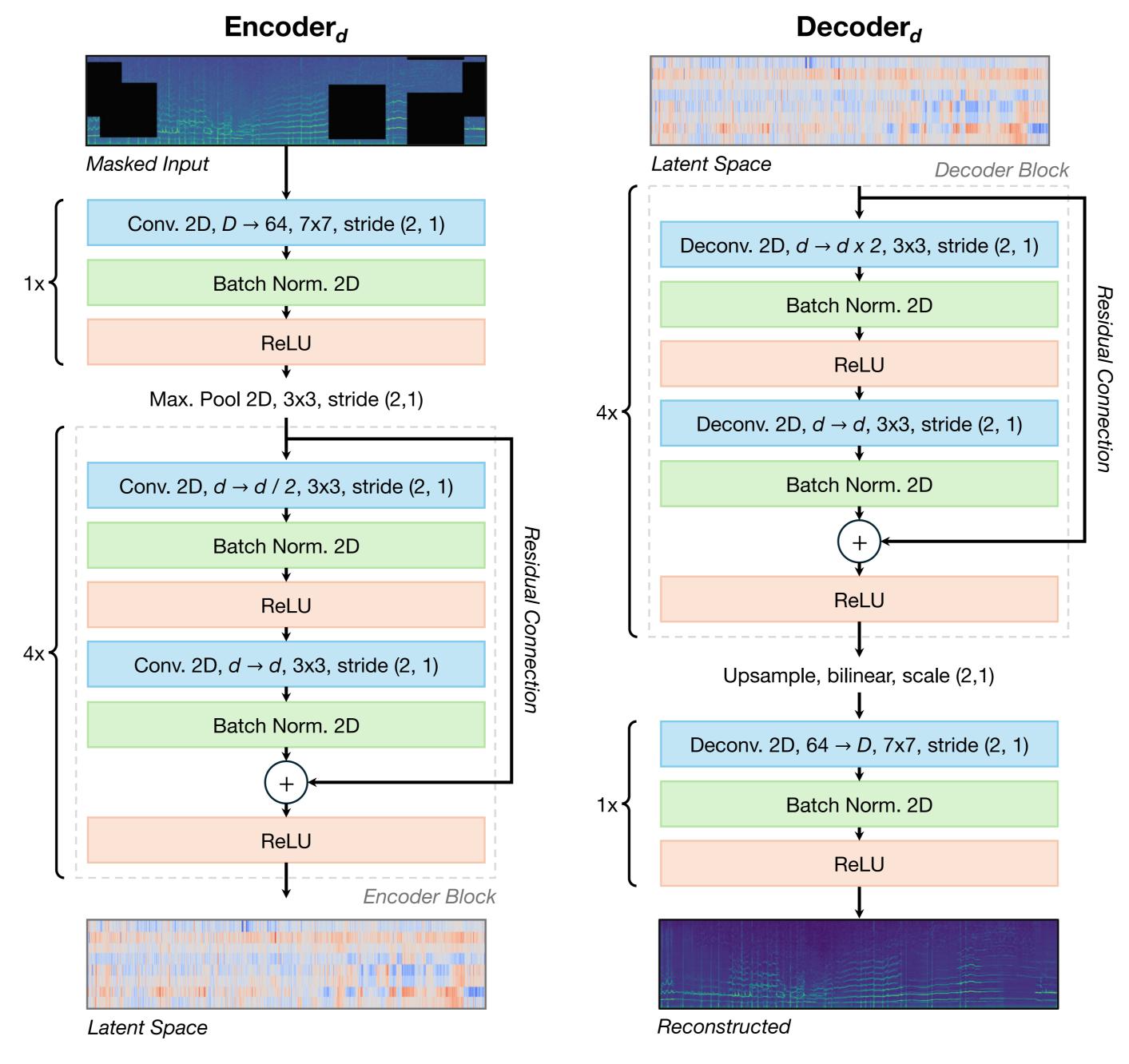
- Currently ~2500 DIII-D shots used to train with 3 high-res. diagnostics:
 - Electron Cyclotron Emission: 40 channels @ 500 kHz, edge-to-core.
 - CO2 Interferometry: 4 chords @ 1.6 MHz, 3 vertical and 1 radial.
 - High-Speed Magnetic Probes: 8 channels @ 2 MHz.
- Resampled to 500 kHz and re-aligned in time.
- Converted to spectrograms using shared STFT parameters.

Architecture



- Each diagnostic is assigned an encoder/decoder pair.
- Encode/reconstruct the spectrogram to/from its latent representation.
- During training ~75% of spectrogram is masked out and reconstructed.

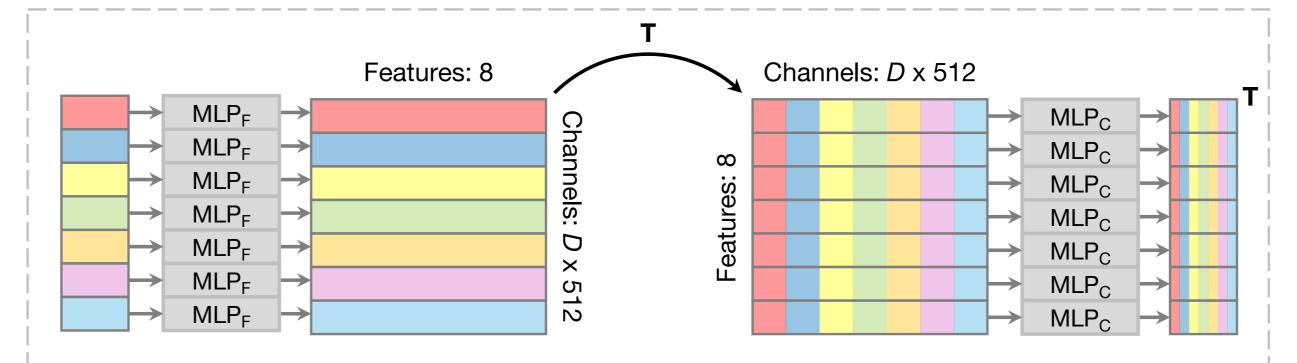
Encoding & Decoding



- Down-/Upsample in frequency dimension using 2D convolution blocks.
- Encoder based on ResNet [2] backbone, decoder mirrors encoder.
- Trained using Mean Squared Error (MSE) on the unmasked spectrograms.

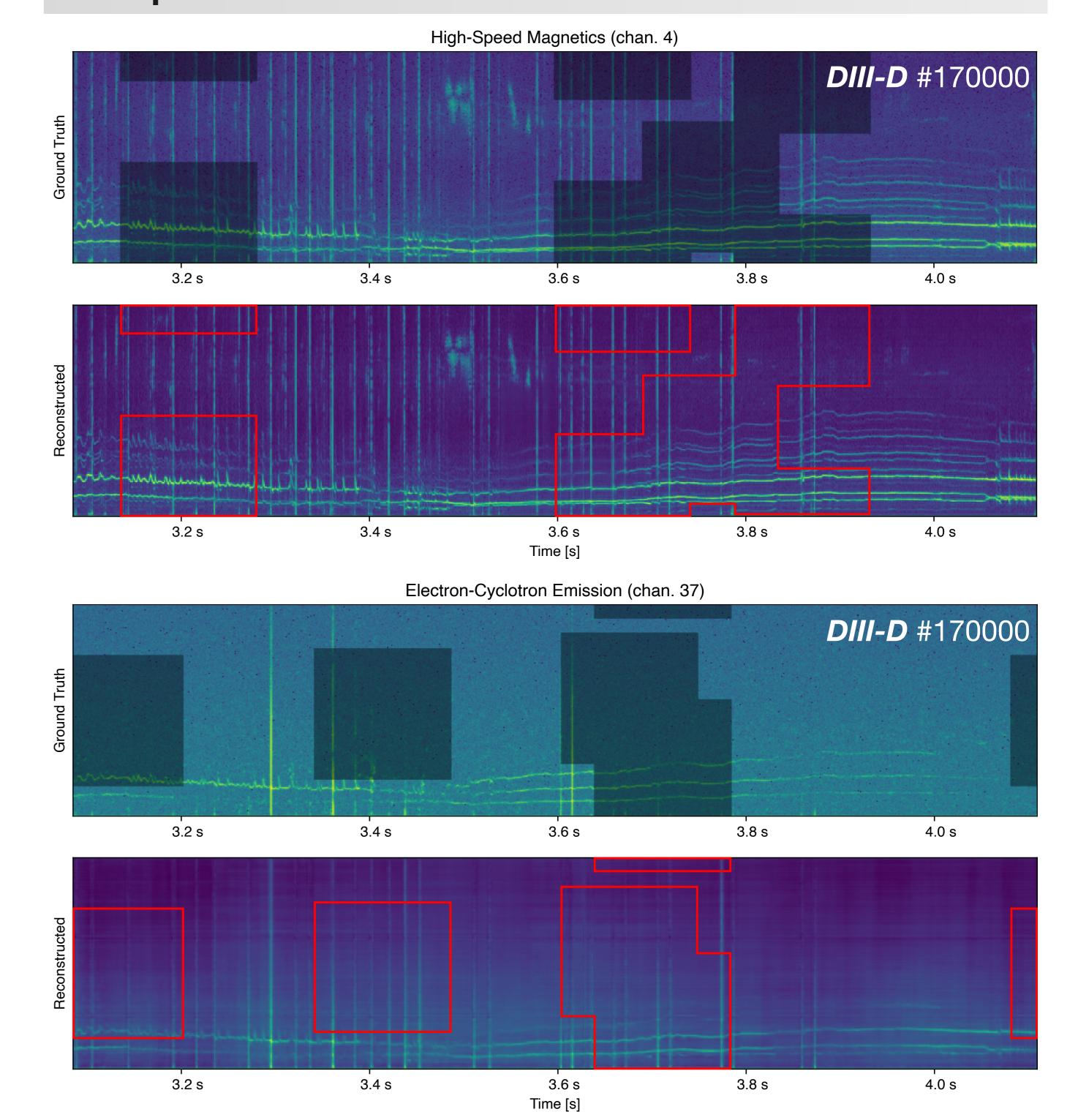
Latent Space Mixing

Feature/Channel Mixing



- Inspired by *MLP-Mixer* [3], replace convolution/attention with simple MLPs that **mix information** along different dimensions separately.
- First mix across frequency bins, then mix across diagnostic channels.
- Single linear layer per dimension, avoiding quadratic parameter growth.
- Channel mixing enables information sharing across different diagnostics, learning how to combine their latent representations.

Example Reconstruction



- Shaded regions above are masked out before being input.
- · Red regions below are the same regions reconstructed by the model.

Next Steps

- Scale dataset to data available at DIII-D (~20h of ~300h available so far.)
- Add support for larger number of diagnostics/actuators.
- Add support for mixed sampling rates.
- Investigate and adapt latent space for downstream tasks.
- Mode identification, profile reconstruction, tearing mode prediction, etc...

Conclusion

We demonstrated that self-supervised learning on fusion diagnostic spectrograms enables robust reconstruction of masked regions, establishing a pathway toward a general-purpose foundation model for fusion.